

CONIC SYSTEMS

HD Series

Harmonic Gearing Component Sets



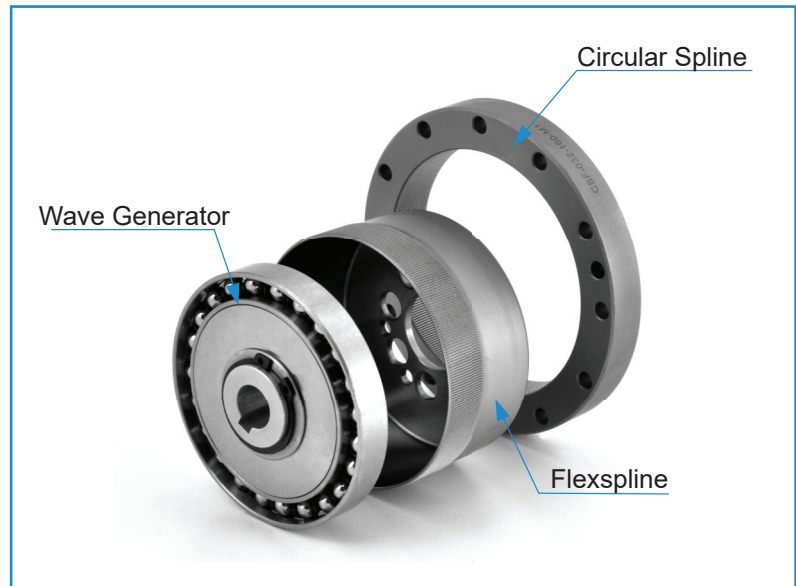
- HDC Zero Backlash Cup Series
- HDF Compact Pancake Series
- HDA Heavy Duty Pancake w/ Hubs
- HDR Heavy Duty Pancake
- HDB Back-to-Back 1:1 Pancake

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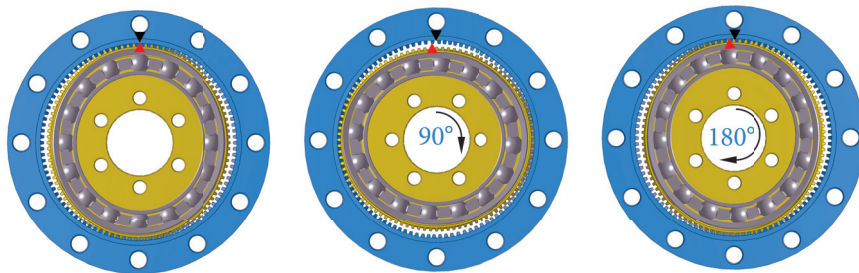
Harmonic Gearing Features and Benefits

- Zero tooth backlash maintained for the life of the unit for cup styles and low backlash for pancake styles
- Positional accuracy of ± 1.5 arc-min and ± 0.5 arc-min by request
- Repeatability typically within a few arc-sec
- Single stage, high reduction ratios of 50:1 to 160:1
- Low noise and heat generation
- High efficiency, torsional stiffness and torque-to-weight ratio
- High torque capacity with a large number of teeth sharing load

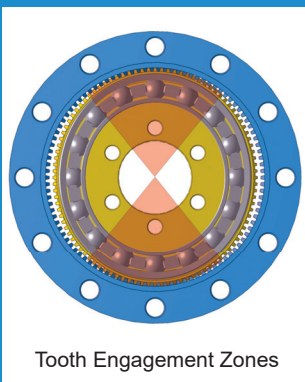


Harmonic Gearing Tooth Engagement

Tooth engagement between the flexspline and the circular spline takes place at two areas located 180° to each other on the ellipse's major axis. The rotation of the wave generator inside the flexspline generates relative motion between the two splines.

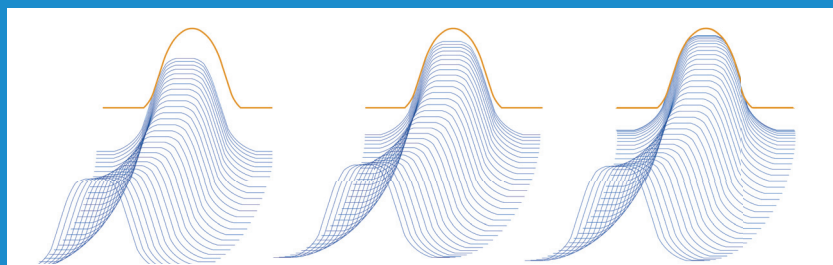


Example: With 100:1 ratio, 100 clockwise input motor rotations result in 1 counterclockwise output rotation.



Tooth Engagement Zones

Characteristically, 30-40 percent of the teeth are engaged dependent upon the ratio, and load is shared amongst many teeth giving the drive its high torque capacity.



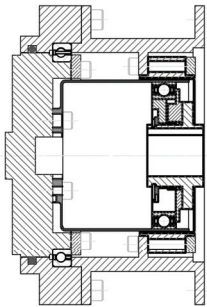
HDC Zero Backlash Cup Series

The HDC Series is a traditional, zero backlash harmonic gear set. It is an excellent choice for applications where axial space is not critical. The standard HDC includes an Oldham coupling on the wave generator input. For zero lost motion between the input motor shaft and wave generator, the wave generator can be modified for direct mounting to the input shaft. Conic manufactures three versions to easily meet most replacement applications without any modifications.



HDC Installation Examples and Model Options

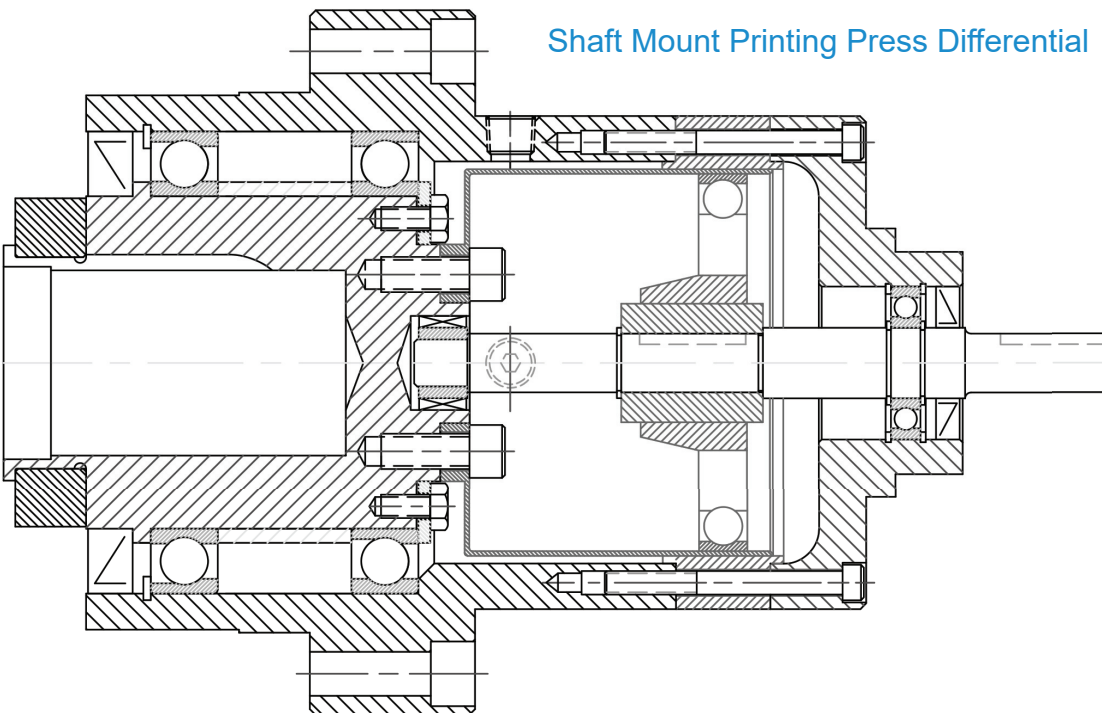
Speed Reducer



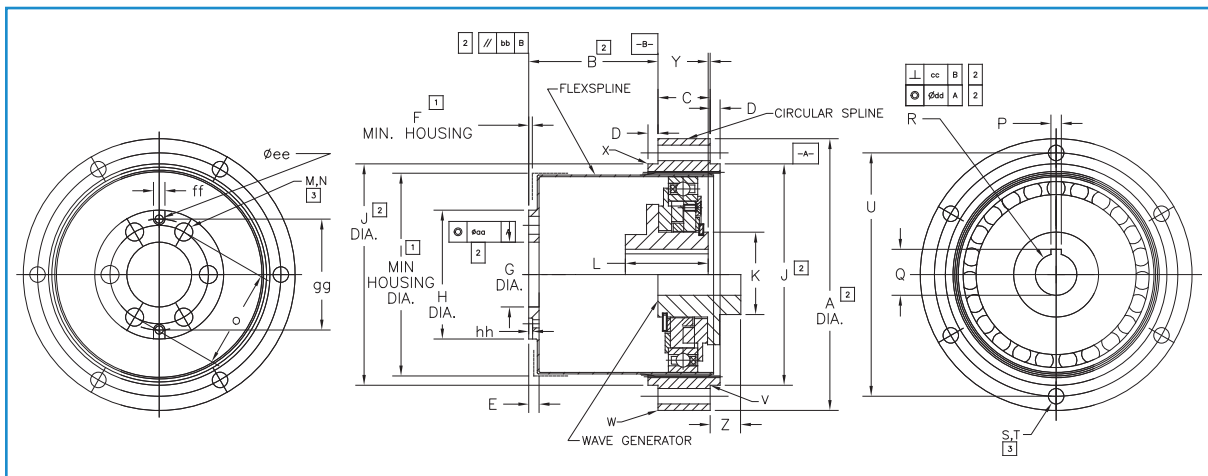
The HDC Series is offered in three model options:

- E1 – English dimensioned unit that is a bolt-in replacement for early harmonic gearing sets manufactured in the USA. The flexspline mounting flange is thinner than the E2 version.
 - E2 – English dimensioned unit that is a bolt-in replacement for units previously manufactured in Japan. The flexspline mounting flange is thicker than the E1 version.
- E1 and E2 units are interchangeable if care is taken to ensure proper mounting bolt lengths are used.
- M1 – Industry standard metric dimensioned version.

Shaft Mount Printing Press Differential



HDC-E1 Dimensions



	1C	3C	5C	1M	2M	4M	8M	15M
ØA	2.0	2.625	3.28	4.250	5.25	6.63	8.63	10.63
B	.940 ± .015	1.270 ± .015	1.560 ± .015	2.030 ± .015	2.50 ± .020	3.204 ± .025	4.160 ± .035	5.060 ± .040
C	.38	.50	.63	.81	1.00	1.09	1.44	1.88
D	.09	.11	.12	.13	.14	.16	.19	.25
E	.125	.125	.135	.197	.260	.260	.322	.388
F	.08	.04	.08	.08	.11	.06	.10	.12
ØG	.4375 ^{+0.0007} / ₋₀	.6255 ^{+0.0005} / ₋₀	.7817 ^{+0.0005} / ₋₀	1.0631 ^{+0.0006} / ₋₀	1.2818 ^{+0.0006} / ₋₀	1.6257 ^{+0.0007} / ₋₀	2.0945 ^{+0.0008} / ₋₀	2.5633 ^{+0.0008} / ₋₀
ØH	.830	1.244	1.555	2.000	2.520	3.125	4.055	5.000
ØI	1.47	2.06	2.58	3.33	4.12	5.15	6.67	8.24
ØJ	1.5000 ⁺⁰ / _{-.0012}	2.1410 ⁺⁰ / _{-.0012}	2.6723 ⁺⁰ / _{-.0025}	3.5005 ⁺⁰ / _{-.0012}	4.2818 ⁺⁰ / _{-.0013}	5.3445 ⁺⁰ / _{-.0028}	6.9539 ⁺⁰ / _{-.0029}	8.5634 ⁺⁰ / _{-.0032}
ØK	.551	.826	1.023 ⁺⁰ / _{-.001}	1.023 ⁺⁰ / _{-.001}	1.260 ⁺⁰ / _{-.001}	1.260 ⁺⁰ / _{-.002}	1.890 ⁺⁰ / _{-.002}	2.165 ^{+0.002} / _{-.002}
L	.63	.750 ⁺⁰ / _{-.010}	1.000 ⁺⁰ / _{-.010}	1.000 ⁺⁰ / _{-.010}	1.500 ⁺⁰ / _{-.010}	1.500 ⁺⁰ / _{-.010}	1.875 ⁺⁰ / _{-.010}	2.437 ⁺⁰ / _{-.010}
M	6	6	6	6	6	6	6	6
ØN	.125 ^{+0.010} / _{-.002}	.187 ^{+0.010} / _{-.002}	.218 ^{+0.010} / _{-.002}	.343 ^{+0.010} / _{-.002}	.406 ^{+0.010} / _{-.002}	.406 ^{+0.010} / _{-.002}	.531 ^{+0.010} / _{-.002}	.781 ^{+0.010} / _{-.002}
ØO	.656	.937	1.187	1.531	1.875	2.312	3.062	3.750
P	.062 PIN	.0937 ^{+0.002} / ₋₀	.125 ^{+0.002} / ₋₀	.125 ^{+0.002} / ₋₀	.1875 ^{+0.002} / ₋₀	.1875 ^{+0.002} / ₋₀	.1875 ^{+0.002} / ₋₀	.250 ^{+0.002} / ₋₀
Q	NA	.415 ^{+0.015} / ₋₀	.555 ^{+0.015} / ₋₀	.555 ^{+0.015} / ₋₀	.710 ^{+0.010} / ₋₀	.710 ^{+0.015} / ₋₀	.959 ^{+0.015} / ₋₀	1.236 ^{+0.015} / ₋₀
ØR	.250 ^{+0.001} / ₋₀	.3750 ^{+0.0004} / ₋₀	.5000 ^{+0.0004} / ₋₀	.5000 ^{+0.0004} / ₋₀	.6250 ^{+0.0005} / ₋₀	.6250 ^{+0.0005} / ₋₀	.8750 ^{+0.0005} / ₋₀	1.1250 ^{+0.0006} / ₋₀
S	6	6	6	6	6	6	6	8
ØT	.125 ^{+0.003} / _{-.002}	.147 ^{+0.003} / _{-.002}	.187 ^{+0.010} / _{-.002}	.218 ^{+0.010} / _{-.002}	.281 ^{+0.010} / _{-.002}	.406 ^{+0.010} / _{-.002}	.468 ^{+0.010} / _{-.002}	.468 ^{+0.010} / _{-.002}
ØU	1.75	2.375	2.937	3.812	4.687	5.875	7.625	9.500
V	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.
W	.016	.016	.015	.015	.015	.015	.015	.015
X	.016	.016	.015	.015	.015	.015	.015	.015
Y	.005 ⁺⁰ / _{-.010}	.028	.067	.099	.075	.047	.105	.088
Z	NA	.242	.361	.211	.569	.448	.562	.787
aa	.002 T.I.R.	.0017 T.I.R.	.0018 T.I.R.	.0019 T.I.R.	.0024 T.I.R.	.0026 T.I.R.	.0027 T.I.R.	.0035 T.I.R.
bb	.001	.0011	.001	.0017	.0019	.0024	.0027	.003
cc	.001	.002	.002	.002	.002	.002	.002	.002
dd	.004 T.I.R.	.0017 T.I.R.	.0018 T.I.R.	.0019 T.I.R.	.0024 T.I.R.	.0026 T.I.R.	.0027 T.I.R.	.0035 T.I.R.
ee	.098	.116	.116	.125	.135	.236	.236	.236
ff	.105	.116	.116	.125	.135	.236	.236	.236
gg	.656	.937	1.343	1.687	2.207	2.312	3.062	3.750
hh	.05	.05	.05	.05	.05	.05	.05	.05

1 DIMENSIONS DENOTE MAXIMUM EXTENT OF ENCROACHMENT ADJOINING STRUCTURE.

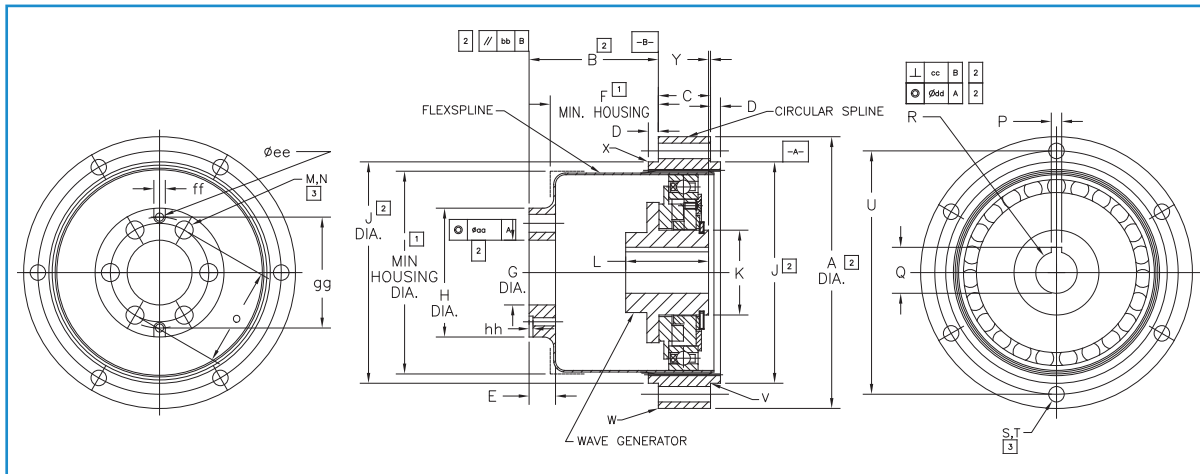
2 DIMENSIONS ESTABLISH INTERFACE AND INSTALLATION REQUIREMENTS. MAINTAIN AT ASSEMBLY AND UNDER ALL OPERATING LOAD CONDITIONS.

3 USE ALLOY STEEL SCREWS TORQUED TO MAXIMUM RECOMMENDED VALUE. USE THREAD LOCKER OR OTHER MEANS TO PREVENT LOOSENING.

4 MAINTAINING STANDARD COMPONENTS IN "AS RECEIVED" SETS IS RECOMMENDED.

5 DRAWING IS FOR DIMENSIONAL REVIEW ONLY.
DO NOT SCALE

HDC-E2 Dimensions



	1C	3C	5C	1M	2M	4M	8M	15M
ØA	2.0	2.630	3.28	4.250	5.25	6.63	8.63	10.63
B	.940 ± .015	1.270 ± .015	1.560 ± .015	2.030 ± .015	2.50 ± .020	3.204 ± .025	4.160 ± .035	5.060 ± .040
C	.38	.50	.63	.81	1.00	1.09	1.44	1.88
D	.09	.11	.12	.12	.14	.16	.19	.25
E	.247	.285	.320	.386	.440	.505	.656	CONSULT
F	.791	1.09	1.34	1.75	2.20	2.85	3.69	CONSULT
ØG	.4375 ^{+0.0007} ₋₀	.6255 ^{+0.0005} ₋₀	.7817 ^{+0.0005} ₋₀	1.0625 ^{+0.0008} ₋₀	1.2818 ^{+0.0006} ₋₀	1.6250 ^{+0.0007} ₋₀	2.0937 ^{+0.0008} ₋₀	CONSULT
ØH	.906	1.244	1.555	2.047	2.520	3.110	4.055	5.000
ØI	1.50	2.09	2.56	3.31	4.10	5.12	6.66	8.24
ØJ	1.5000 ⁺⁰ _{-.0012}	2.1410 ⁺⁰ _{-.0012}	2.6723 ⁺⁰ _{-.0025}	3.5005 ⁺⁰ _{-.0012}	4.2818 ⁺⁰ _{-.0013}	5.3445 ⁺⁰ _{-.0028}	6.9539 ⁺⁰ _{-.0029}	8.5634 ⁺⁰ _{-.0032}
ØK	.551	.827	1.024	1.024	1.260	1.260	1.890	2.165
L	.630	.750	1.000	1.000	1.500	1.500	1.880	2.437
M	6	6	6	6	6	6	6	6
ØN	.125 ^{+0.010} _{-.002}	.187 ^{+0.010} _{-.002}	.218 ^{+0.010} _{-.002}	.343 ^{+0.010} _{-.002}	.406 ^{+0.010} _{-.002}	.406 ^{+0.010} _{-.002}	.531 ^{+0.010} _{-.002}	.781 ^{+0.010} _{-.002}
ØO	.656	.937	1.187	1.531	1.875	2.312	3.062	3.750
P	(2) 4-40 Set Screw	.0937 ^{+0.002} ₋₀	.125 ^{+0.002} ₋₀	.125 ^{+0.002} ₋₀	.1875 ^{+0.002} ₋₀	.1875 ^{+0.002} ₋₀	.1875 ^{+0.002} ₋₀	.250 ^{+0.002} ₋₀
Q	NA	.415 ^{+0.015} ₋₀	.555 ^{+0.015} ₋₀	.555 ^{+0.015} ₋₀	.704 ^{+0.015} ₋₀	.704 ^{+0.015} ₋₀	.959 ^{+0.015} ₋₀	1.236 ^{+0.015} ₋₀
ØR	.250 ^{+0.001} ₋₀	.375 ^{+0.001} ₋₀	.500 ^{+0.001} ₋₀	.500 ^{+0.001} ₋₀	.625 ^{+0.001} ₋₀	.625 ^{+0.001} ₋₀	.875 ^{+0.001} ₋₀	1.1250 ^{+0.0006} ₋₀
S	6	6	6	6	6	6	6	8
ØT	.125 ^{+0.003} _{-.002}	.147 ^{+0.010} _{-.002}	.187 ^{+0.010} _{-.002}	.218 ^{+0.010} _{-.002}	.281 ^{+0.010} _{-.002}	.406 ^{+0.010} _{-.002}	.468 ^{+0.010} _{-.002}	.468 ^{+0.010} _{-.002}
ØU	1.75	2.375	2.937	3.812	4.687	5.875	7.625	9.500
V	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.	.005R MAX.
W	.016	.016	.015	.015	.015	.015	.015	.015
X	.016	.016	.015	.015	.015	.015	.015	.015
Y	.010 ⁺⁰ _{-.010}	.028	.067	.099	.075	.047	.105	.088
Z	NA	.242	.361	.211	.569	.448	.562	.787
aa	.002 T.I.R.	.002 T.I.R.	.002 T.I.R.	.003 T.I.R.	.004 T.I.R.	.005 T.I.R.	.007 T.I.R.	.007 T.I.R.
bb	.001	.001	.001	.001	.001	.001	.001	.003
cc	.001	.002	.002	.002	.002	.002	.002	.002
dd	.004 T.I.R.	.004 T.I.R.	.005 T.I.R.	.005 T.I.R.	.006 T.I.R.	.006 T.I.R.	.007 T.I.R.	.007 T.I.R.
ee	.098	.116	.116	.125	.135	.236	.236	.236
ff	.105	.116	.116	.125	.135	.236	.236	.236
gg	.656	.937	1.343	1.687	2.207	2.312	3.062	3.750
hh	.05	.05	.05	.05	.05	.05	.05	.05

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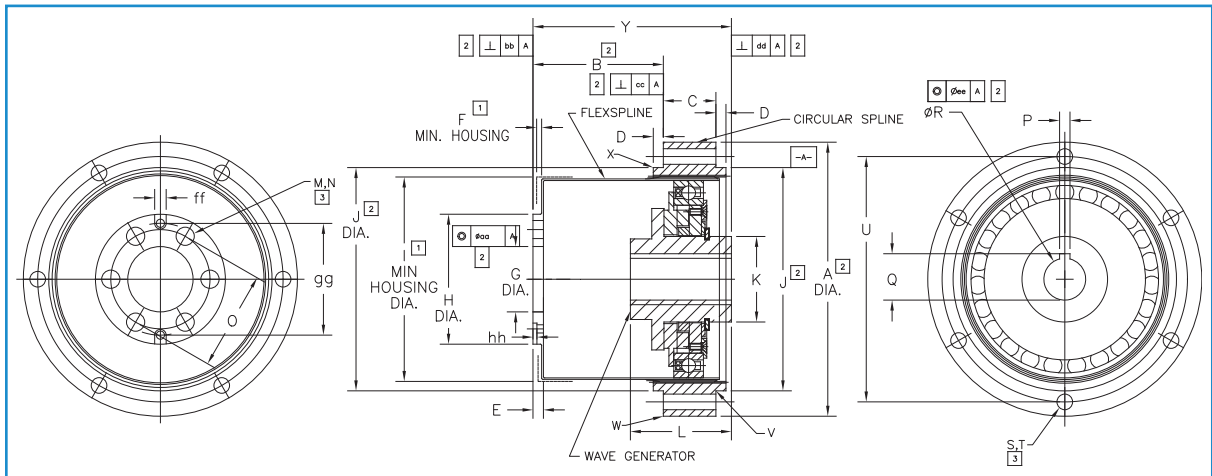
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HDC-M1 Dimensions



	20	25	32	40	50	65	80	100
ØA	70 ⁺⁰ _{-.019}	85 ⁺⁰ _{-.022}	110 ⁺⁰ _{-.022}	135 ⁺⁰ _{-.025}	170 ⁺⁰ _{-.025}	215 ⁺⁰ _{-.029}	265 ⁺⁰ _{-.029}	330 ⁺⁰ _{-.036}
B	31.3 ± .3	40.3 ± .3	52.3 ± .3	63.3 ± .3	80.3 ± .3	100.3 ± .3	119.3 ± .3	153.5 ± .5
C	14	16	20	25	30	40	50	60
D	3	3	3	4	4	5	6	6
E	5.4	6.5	8.6	9.5	13.0	16.3	14.6	18
F	2	2	2	3	3	4	5	6
ØG	16 ^{+.011} ₋₀	20 ^{+.013} ₋₀	26 ^{+.013} ₋₀	32 ^{+.016} ₋₀	40 ^{+.016} ₋₀	52 ^{+.019} ₋₀	65 ^{+.019} ₋₀	80 ^{+.019} ₋₀
ØH	31.6	39.5	52	64	79	103	126	158
ØI	52.3	65	84.6	104.6	131	169.4	209.3	261
ØJ	54 ⁺⁰ _{-.019}	67 ⁺⁰ _{-.019}	90 ⁺⁰ _{-.022}	110 ⁺⁰ _{-.022}	135 ⁺⁰ _{-.025}	177 ⁺⁰ _{-.025}	218 ⁺⁰ _{-.029}	272 ⁺⁰ _{-.032}
ØK	21	26	26	32	32	48	55	65
L	27 ⁺⁰ _{-.1}	32 ⁺⁰ _{-.1}	32 ⁺⁰ _{-.1}	40 ⁺⁰ _{-.1}	40 ⁺⁰ _{-.1}	52 ⁺⁰ _{-.1}	65 ⁺⁰ _{-.1}	70 ⁺⁰ _{-.1}
M	6	6	6	6	6	6	12	12
ØN	4.5	5.5	6.6	9	14	14	11	14
ØO	24	30	40	50	60	80	104	130
P	3 ± .0125	4 ± .0150	5 ± .0150	5 ± .0150	6 ± .0150	8 ± .0180	8 ± .0180	8 ± .0180
Q	10.4	12.8	16.3	16.3	21.8	27.3	31.3	31.3
ØR	9 ^{+.015} ₋₀	11 ^{+.018} ₋₀	14 ^{+.018} ₋₀	14 ^{+.018} ₋₀	19 ^{+.021} ₋₀	24 ^{+.021} ₋₀	28 ^{+.021} ₋₀	28 ^{+.021} ₋₀
S	6	6	6	6	6	6	8	8
ØT	3.5	4.5	5.5	6.6	9	11	11	14
ØU	60	75	100	120	150	195	240	290
V	.3	.3	.3	.3	.3	.3	.3	.3
W	.4	.4	.4	.4	.4	.4	.4	.4
X	.4	.4	.4	.4	.4	.4	.4	.4
Y	51.5 ± .5	63.5 ± .5	77.5 ± .6	95.5 ± .6	116.4 ± .7	146.3 ± .7	177.3 ± .7	220.2 ± .7
aa	.044	.047	.050	.063	.066	.070	.090	.110
bb	.028	.036	.044	.050	.060	.070	.080	.090
cc	.031	.033	.035	.045	.047	.049	.064	.080
dd	.025	.036	.036	.048	.048	.048	.054	.060
ee	.044	.047	.050	.063	.066	.070	.090	.110
ff	2.66	2.94	2.94	3.17	3.94	6	6	6
gg	16.66	23.80	34.11	42.85	56.06	58.72	77.77	95.25
hh	1.27	1.27	1.27	1.27	1.27	1.27	1.27	1.27

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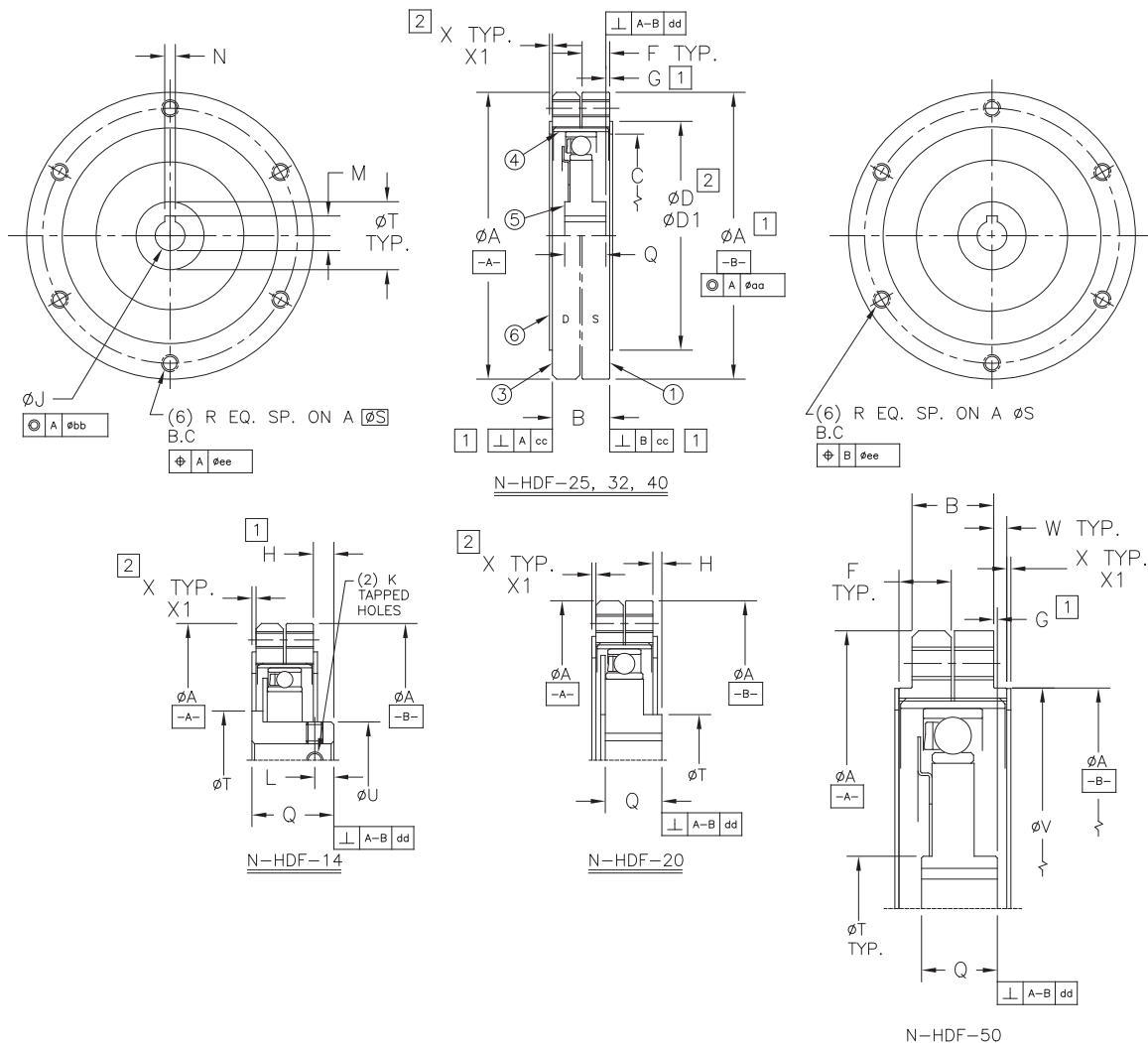
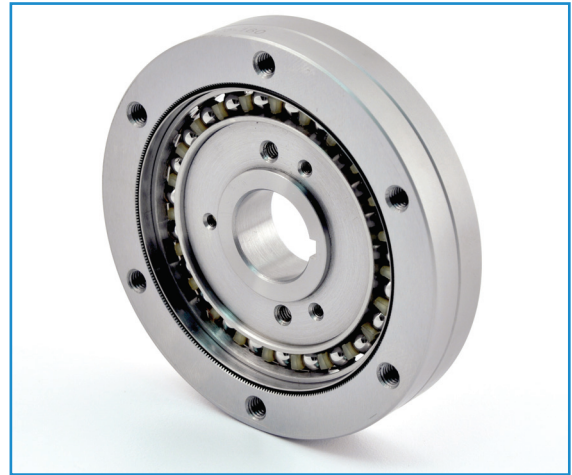
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HDC Specifications

Size	Ratio	Input Speed 3000rpm			Input Speed 1500rpm			Input Speed 1000rpm		
		Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power
		Nm	rpm	kw	Nm	rpm	kw	Nm	rpm	kw
English: 1C	64	4.5	46.9	0.025	4.5	23.4	0.012	4.5	15.6	0.008
	80	5	37.5	0.025	5.5	18.8	0.013	5.5	12.5	0.009
Metric: 17	80	12	37.5	0.059	12	18.8	0.029	12	12.5	0.019
	100	15	30	0.059	16.5	15	0.031	17	10	0.021
English: 3C Metric: 20	80	25	37.5	0.123	25	18.8	0.059	25	12.5	0.039
	84	25	35.7	0.117	25	17.9	0.056	25	11.9	0.037
	100	30	30	0.118	33	15	0.062	33.6	10	0.041
	125	30	24	0.097	37.5	12	0.058	43.5	8	0.044
English: 5C Metric: 25	80	40	37.5	0.197	40	18.8	0.094	40	12.5	0.062
	100	50	30	0.197	55	15	0.104	56	10	0.069
	120	50	25	0.169	62.5	12.5	0.101	72.5	8.3	0.074
	150	50	20	0.146	62.5	10	0.085	72.5	6.7	0.062
	160	50	18.8	0.139	62.5	9.4	0.078	72.5	6.3	0.057
English: 1M Metric: 32	80	100	37.5	0.493	100	18.8	0.235	100	12.5	0.153
	100	120	30	0.473	132	15	0.248	135	10	0.165
	135	120	22.2	0.363	150	11.2	0.215	175	7.5	0.163
	160	120	18.8	0.312	150	9.4	0.185	175	6.3	0.140
	200	120	15	0.264	150	7.5	0.156	175	5	0.118
English: 2M Metric: 40	80	200	37.5	0.986	200	18.8	0.469	200	12.5	0.305
	84	200	35.7	0.939	200	17.9	0.447	200	11.9	0.291
	100	240	30	0.947	265	15	0.497	270	10	0.330
	125	240	24	0.777	300	12	0.462	300	8	0.300
	160	240	18.8	0.624	300	9.4	0.370	300	6.3	0.240
	168	240	17.9	0.594	300	8.9	0.352	300	6	0.228
	200	240	15	0.527	300	7.5	0.312	300	5	0.202
English: 4M Metric: 50	80	360	37.5	1.775	360	18.8	0.844	360	12.5	0.549
	100	450	30	1.775	495	15	0.929	505	10	0.617
	120	450	25	1.518	550	12.5	0.881	600	8.3	0.625
	150	450	20	1.25	550	10	0.723	600	6.7	0.513
	160	450	18.8	1.169	550	9.4	0.678	600	6.3	0.481
	200	450	15	0.989	550	7.5	0.572	600	5	0.405
English: 8M Metric: 65	80				800	18.8	1.876	800	12.5	1.221
	100				900	15	1.689	1015	10	1.282
	134				1000	11.2	1.435	1150	7.5	1.073
	160				1000	9.4	1.233	1150	6.3	0.921
	200				1000	7.5	1.040	1150	5	0.776
	267				1000	5.6	0.823	1150	3.7	0.614
English: 15M Metric: 80	80				1500	18.8	3.518	1500	12.5	2.289
	100				1800	15	3.377	2000	10	2.442
	125				2000	12	3.077	2300	8	2.301
	168				2000	8.9	2.348	2300	6	1.755
	200				2000	7.5	2.079	2300	5	1.552
	250				2000	6	1.758	2300	4	1.311
Metric: 100	80				2500	18.8	5.863	2500	12.5	3.816
	100				3500	15	6.567	3650	10	4.457
	120				3500	12.5	5.609	4000	8.3	4.169
	150				3500	10	4.602	4000	6.7	3.419
	160				3500	9.4	4.315	4000	6.3	3.205
	200				3500	7.5	3.638	4000	5	2.699
	250				3500	6	3.077	4000	4	2.280
	315				3500	4.8	2.514	4000	3.2	1.920

HDF Compact Pancake Series

The HDF Series offers the shortest axial length of all harmonic gearing components. It is designed for applications where space is the primary constraint. The drive utilizes a single wave generator bearing and is recommended for light duty speed reduction and phase shifting applications. The HDF offers low backlash, standard ratios ranging from 64:1 to 200:1, and torque capacities up to 1000 Nm. Custom drives are available upon request.



HDF-M1 Dimensions

	14	20	25	32	40	50
ØA	50 ⁺⁰ _{-.015}	70 ⁺⁰ _{-.018}	85 ⁺⁰ _{-.023}	110 ⁺⁰ _{-.025}	135 ⁺⁰ _{-.025}	170 ⁺⁰ _{-.025}
B	10.7 ± .15	12.7 ± .15	17 ± .25	21 ± .25	27 ± .30	25 ± .30
ØC	32 ± .51	47 ± .51	59 ± .51	77 ± .51	95 ± .51	119 ± .51
ØD	39.5 ± .51	54 ± .51	69.4 ± .51	92.1 ± .51	111.1 ± .51	134.4 ± .51
ØD1	40.2 ± .51	54.7 ± .51	70.2 ± .51	92.9 ± .51	111.9 ± .51	135.2 ± .51
F	5 ± .1	6 ± .1	8 ± .2	10 ± .2	13 ± .2	16 ± .2
G	-	-	.38 ± .38	.94 ± .38	1.8 ± .38	1.12 ± .38
H	3.76 ± .38	.94 ± .38	-	-	-	-
ØJ	6 ^{+0.012} ₋₀	9 ^{+0.015} ₋₀	11 ^{+0.018} ₋₀	14 ^{+0.020} ₋₀	14 ^{+0.020} ₋₀	19 ^{+0.020} ₋₀
K	M3 x 0.5	-	-	-	-	-
L	3.5 ± .38	-	-	-	-	-
ØM	-	10.4 ⁺¹ ₋₀	12.8 ⁺¹ ₋₀	16.3 ⁺¹ ₋₀	16.3 ⁺¹ ₋₀	21.8 ⁺¹ ₋₀
N	-	3 ± .0125	4 ± .013	5 ± .013	5 ± .013	6 ± .013
Q	15.0	11.4	12.8	15.6	19.4	23.2
R	M3 x 0.5	M4 x 0.7	M5 x 0.8	M6 x 1.0	M8 x 1.25	M10 x 1.5
S	44	60	75	100	120	150
ØT	18	20	28	36	32	50
ØU	14	-	-	-	-	-
ØV	-	-	-	-	-	135 ⁺⁰ _{-.025}
W	-	-	-	-	-	4.52 ± .1
X	.81 ± .13	.81 ± .13	.81 ± .13	.81 ± .13	1.57 ± .13	1.57 ± .13
X1	.94 ^{+1.13} ₋₀	.94 ^{+1.13} ₋₀	.94 ^{+1.13} ₋₀	.94 ^{+1.13} ₋₀	1.70 ^{+1.13} ₋₀	1.70 ^{+1.13} ₋₀
aa	.050	.070	.076	.078	.088	.098
bb	.013	.013	.015	.015	.018	.020
cc	.018	.018	.023	.025	.025	.025
dd	.010	.010	.013	.013	.013	.015
ee	.25	.25	.25	.25	.25	.25
Weight kg (lb)	.09 (.2)	.32 (.7)	.59 (1.3)	1.04 (2.3)	2 (4.4)	3.31 (7.3)

- [A] ITEM 1 STATIC CIRCULAR SPLINE MARKED "S"
 ITEM 2 ONLY APPEARS WITH HDR & HDA
 ITEM 3 DYNAMIC CIRCULAR SPLINE MARKED "D"
 ITEM 4 FLEXSPLINE
 ITEM 5 WAVE GENERATOR
 ITEM 6 WEAR WASHERS

- [B] DIMENSIONS MARKED 1 ESTABLISH INTERFACE AND INSTALLATION REQUIREMENTS, AND MUST BE MAINTAINED UNDER ALL OPERATING CONDITIONS.
 [C] DIMENSIONS MARKED 2 ARE NECESSARY TO LOCATE WEAR WASHERS, ITEM 6, IN CORRECT POSITION.
 [D] HDF 50 CAN BE LOCATED ON THE OUTER DIAMETER OF THE CIRCULAR SPLINE, DIMENSION A, OR ON THE PLOT DIAMETER DIMENSION V.
 [E] DRAWING IS FOR DIMENSIONAL REVIEW ONLY. **DO NOT SCALE**

HDF Specifications

Size	Ratio	Input Speed 3000rpm			Input Speed 1500rpm			Input Speed 1000rpm		
		Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power
		Nm	rpm	kw	Nm	rpm	kw	Nm	rpm	kw
14	64	3	46.9	0.023	3	23.4	0.012	3.5	15.6	0.009
	80	3.5	37.5	0.022	3.5	18.8	0.011	4	12.5	0.009
20	80	15	37.5	0.096	15	18.8	0.049	15	12.5	0.033
	84	15	35.7	0.092	15	17.9	0.047	15	11.9	0.031
	100	18	30	0.092	20	15	0.052	22	10	0.038
	120	20	25	0.085	22.5	12.5	0.049	25	8.3	0.036
	126	20	23.8	0.081	22.5	11.9	0.047	25	7.9	0.034
25	80	25	37.5	0.160	25	18.8	0.082	27.5	12.5	0.060
	100	30	30	0.154	33	15	0.086	35	10	0.061
	120	32	25	0.137	35	12.5	0.076	38	8.3	0.055
	150	36	20	0.134	40	10	0.070	43.5	6.7	0.051
	160	36	18.8	0.126	40	9.4	0.066	40	6.3	0.043
32	80	55	37.5	0.353	55	18.8	0.180	55	12.5	0.120
	100	70	30	0.359	77	15	0.202	80	10	0.140
	135	80	22.2	0.332	88	11.1	0.170	97	7.4	0.125
	160	85	18.8	0.297	93.5	9.4	0.153	102	6.3	0.112
	200	85	15	0.238	93.5	7.5	0.122	102	5	0.089
40	80	100	37.5	0.641	100	18.8	0.328	100	12.5	0.218
	84	100	35.7	0.610	100	17.9	0.312	100	11.9	0.208
	100	120	30	0.615	132	15	0.346	135	10	0.236
	125	135	24	0.554	150	12	0.314	150	8	0.209
	160	150	18.8	0.524	165	9.4	0.271	165	6.3	0.181
	168	150	17.9	0.499	165	8.9	0.256	165	6	0.173
50	80	180	37.5	1.154	180	18.8	0.59	180	12.5	0.393
	100	220	30	1.128	240	15	0.628	245	10	0.428
	120	250	25	1.068	275	12.5	0.6	280	8.3	0.406
	150	280	20	1.044	310	10	0.544	320	6.7	0.374
	160	280	18.8	0.979	310	9.4	0.509	320	6.3	0.352
	200	280	17.9	0.783	310	7.5	0.406	320	5	0.279
65	80				480	18.8	1.420	480	12.5	1.047
	100				540	15	1.278	605	10	1.055
	135				625	11.2	1.148	700	7.4	0.904
	160				650	9.4	1.041	715	6.3	0.786
	200				650	7.5	0.833	715	5	0.624
80	80				900	18.8	2.663	900	12.5	1.963
	100				950	15	2.249	990	10	1.728
	125				1000	12	1.985	1100	8	1.536
	168				1000	8.9	1.57	1100	6	1.151
	200				1000	7.5	1.374	1100	5	0.960

HDA Heavy Duty Pancake Series w/Hubs

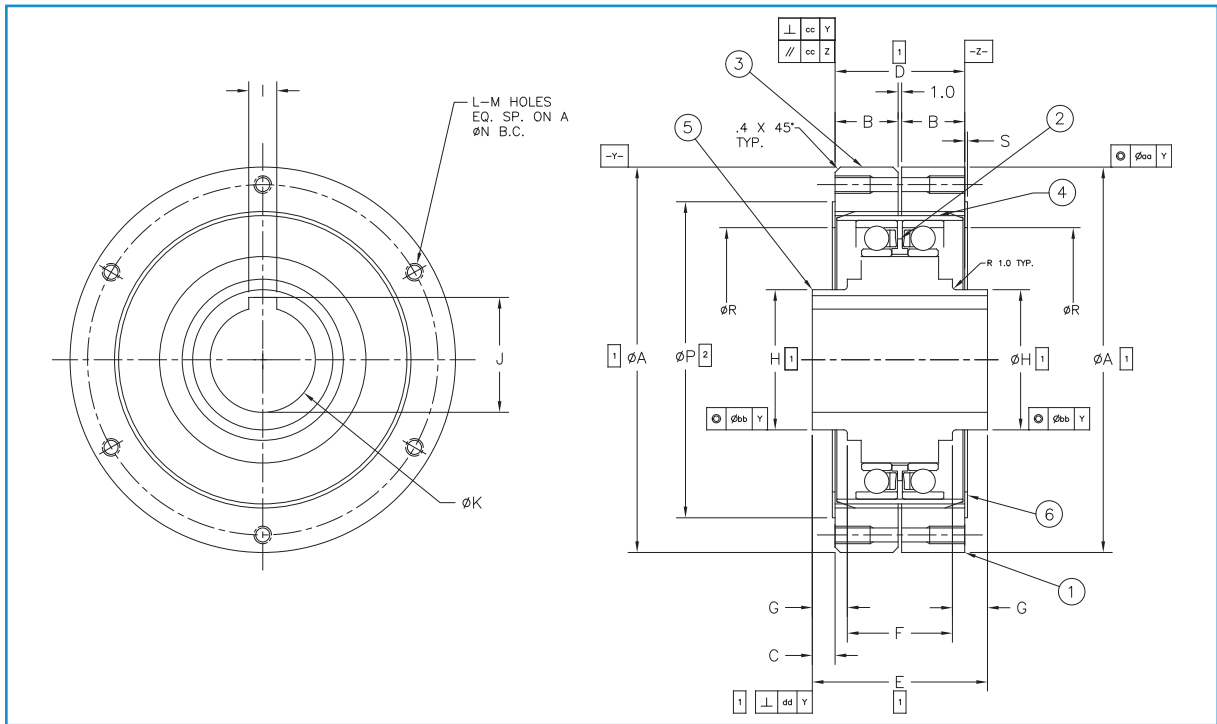
The HDA Series is a heavy duty pancake design that utilizes a double bearing wave generator and wider splines. It also includes an extended wave generator hub for mounting bearings and features a large through bore. The HDA is commonly used in differential applications where shock loads are present, such as corrugated machinery and printing press cutters. The HDA offers low backlash and standard ratios from 80:1 to 200:1 with torque capacities up to 2000 Nm. Custom drives are available upon request.



HDA Specifications

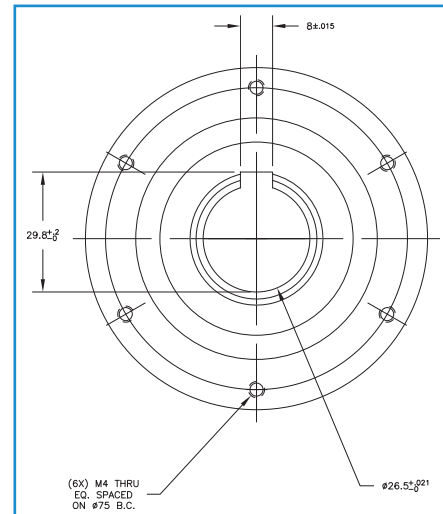
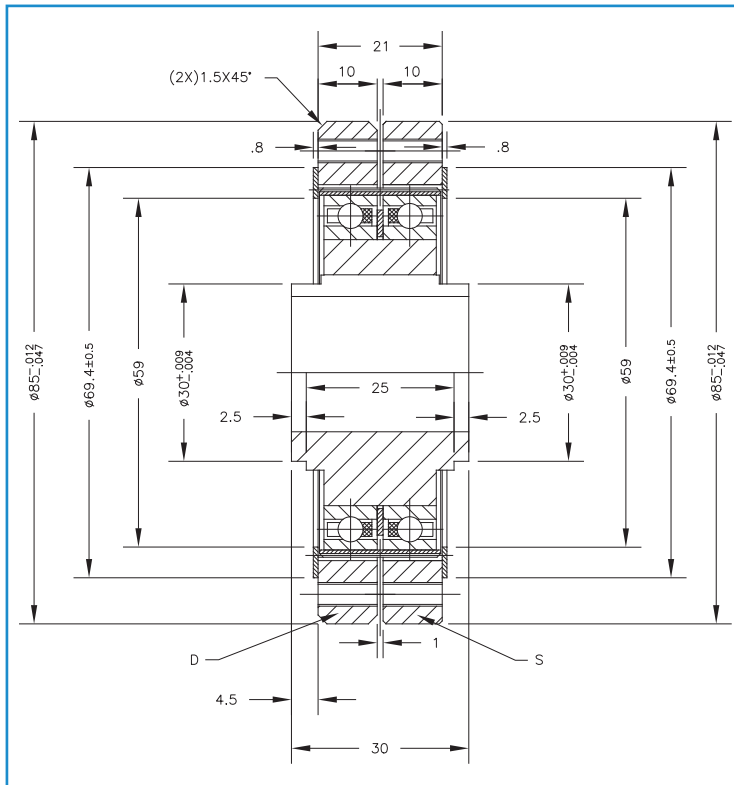
Size	Maximum Input Speed		Ratio	Input Speed 3000 rpm			Input Speed 1500 rpm			Input Speed 1000 rpm		
				Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power
	Grease	Oil		Nm	rpm	kw	Nm	rpm	kw	Nm	rpm	kw
20	3500	5000	80	25	37.5	0.123	25	18.8	0.059	25	12.5	0.039
			84	25	35.7	0.117	25	17.9	0.056	25	11.9	0.037
			100	30	30	0.118	33	15	0.062	33.6	10	0.041
			120	30	25	0.101	37.5	25	0.06	33.6	25	0.042
			126	30	24	0.097	37.5	12	0.058	43.5	8	0.044
25	3000	5000	80	40	37.5	0.197	40	18.8	0.094	40	12.5	0.062
			100	50	30	0.197	55	15	0.104	56	10	0.069
			120	50	25	0.169	62.5	12.5	0.101	72.5	8.3	0.074
			150	50	20	0.146	62.5	10	0.085	72.5	6.7	0.062
			160	50	18.8	0.139	62.5	9.4	0.078	72.5	6.3	0.057
32	3000	4500	80	100	37.5	0.493	100	18.8	0.235	100	12.5	0.153
			100	120	30	0.473	132	15	0.248	135	10	0.165
			135	120	22.2	0.363	150	11.2	0.215	175	7.5	0.163
			160	120	18.8	0.312	150	9.4	0.185	175	6.3	0.014
			200	120	15	0.264	150	7.5	0.156	175	5	0.118
40	3000	4500	80	200	37.5	0.986	200	18.8	0.469	200	12.5	0.305
			84	200	35.7	0.939	200	17.9	0.447	200	11.9	0.291
			100	240	30	0.947	265	15	0.497	270	10	0.33
			125	240	24	0.777	300	12	0.462	300	8	0.3
			160	240	18.8	0.624	300	9.4	0.37	300	6.3	0.24
			168	240	17.9	0.594	300	8.9	0.352	300	6	0.228
			200	240	15	0.527	300	7.5	0.312	300	5	0.202
50	2500	3500	80	360	37.5	1.775	360	18.8	0.844	360	12.5	0.549
			100	450	30	1.775	495	15	0.929	505	10	0.617
			120	450	25	1.518	550	12.5	0.881	600	8.3	0.625
			150	450	20	1.25	550	10	0.723	600	6.7	0.513
			160	450	18.8	1.169	550	9.4	0.678	600	6.3	0.481
			200	450	15	0.989	550	7.5	0.572	600	5	0.405
65	1750	1750	80				800	18.8	1.876	800	12.5	1.221
			96				900	15.6	1.76	1015	10.4	1.335
			100				900	15	1.689	1015	10	1.282
			126				1000	11.9	1.558	1150	7.9	1.162
			132				1000	11.4	1.487	1150	7.6	1.11
			135				1000	11.2	1.454	1150	7.4	1.086
			160				1000	9.4	1.233	1150	6.3	0.921
			200				1000	7.5	1.04	1150	5	0.776
80	1500	1500	80				1500	18.8	3.518	1500	12.5	2.289
			100				1800	15	3.377	2000	10	2.442
			125				2000	12	3.077	2300	8	2.301
			168				2000	8.9	2.348	2300	6	1.755
			200				2000	8.9	2.079	2300	5	1.552
			250				2000	6	1.758	2300	4	1.311

HDA-M1 Dimensions



	20	25	32	40	50	65
ØA	70 $\begin{smallmatrix} -.010 \\ -.040 \end{smallmatrix}$	85 $\begin{smallmatrix} -.012 \\ -.047 \end{smallmatrix}$	110 $\begin{smallmatrix} -.012 \\ -.047 \end{smallmatrix}$	135 $\begin{smallmatrix} -.014 \\ -.054 \end{smallmatrix}$	170 $\begin{smallmatrix} -.014 \\ -.054 \end{smallmatrix}$	215 $\begin{smallmatrix} -.015 \\ -.061 \end{smallmatrix}$
B	12	14	18	21	26	35
C	6.5	5.5	6.5	12.5	12.5	8
D	25	29	37	43	53	71
E	38	40	50	68	78	87
F	21.5	25	30	44	54	59
G	8.25	7.5	10	12	12	14
ØH	20 $\begin{smallmatrix} +.009 \\ -.004 \end{smallmatrix}$	30 $\begin{smallmatrix} +.009 \\ -.004 \end{smallmatrix}$	40 $\begin{smallmatrix} +.011 \\ -.005 \end{smallmatrix}$	50 $\begin{smallmatrix} +.011 \\ -.005 \end{smallmatrix}$	60 $\begin{smallmatrix} +.012 \\ -.007 \end{smallmatrix}$	70 $\begin{smallmatrix} +.012 \\ -.007 \end{smallmatrix}$
I	4 ± .015	6 ± .015	8 ± .018	10 ± .018	12 ± .0215	14 ± .0215
J	13.8	22.8	33.3	38.3	43.3	53.8
ØK	12 $\begin{smallmatrix} +.018 \\ -0 \end{smallmatrix}$	20 $\begin{smallmatrix} +.021 \\ -0 \end{smallmatrix}$	30 $\begin{smallmatrix} +.021 \\ -0 \end{smallmatrix}$	35 $\begin{smallmatrix} +.025 \\ -0 \end{smallmatrix}$	40 $\begin{smallmatrix} +.025 \\ -0 \end{smallmatrix}$	50 $\begin{smallmatrix} +.025 \\ -0 \end{smallmatrix}$
L	6	6	6	6	6	6
M	M3 x 6 DP	M4 x 8 DP	M5 x 10 DP	M6 x 12 DP	M8 x 16 DP	M10 x 20 DP
ØN	60	75	100	120	150	195
ØP	54 ± .5	69.4 ± .5	92 ± .5	111 ± .5	134.4 ± .5	176 ± .5
ØR	47	59	77	95	119	150
S	.8	.8	.8	1.6	1.6	1.6
aa	.016	.016	.017	.019	.024	.027
bb	.013	.016	.016	.017	.021	.025
cc	.017	.024	.026	.026	.028	.034
dd	.010	.012	.012	.012	.015	.015
Weight kg (lb)	.6 (1.3)	1 (2.2)	2 (4.4)	3.6 (7.9)	7.2 (16)	14 (31)

Custom Large Bore Option* (Size 25 Example)



* Customers requiring large bores, custom wave generators or splines are encouraged to contact Conic Systems for availability information. Conic Systems strives to meet its customers' application requirements and will modify its component sets to suit most application needs.

HDA-M1 DRAWING NOTES

- | | |
|--|---|
| <p>A ITEM 1 STATIC CIRCULAR SPLINE MARKED "S"</p> <p>ITEM 2 ONLY APPEARS WITH HDR & HDA</p> <p>ITEM 3 DYNAMIC CIRCULAR SPLINE MARKED "D"</p> <p>ITEM 4 FLEXSPLINE</p> <p>ITEM 5 WAVE GENERATOR</p> <p>ITEM 6 WEAR WASHERS</p> | <p>B DIMENSIONS MARKED 1 ESTABLISH INTERFACE AND INSTALLATION REQUIREMENTS, AND MUST BE MAINTAINED UNDER ALL OPERATING CONDITIONS.</p> <p>C DIMENSIONS MARKED 2 ARE NECESSARY TO LOCATE WEAR WASHERS, ITEM 6, IN CORRECT POSITION.</p> <p>D DRAWING IS FOR DIMENSIONAL REVIEW ONLY.
DO NOT SCALE</p> |
|--|---|

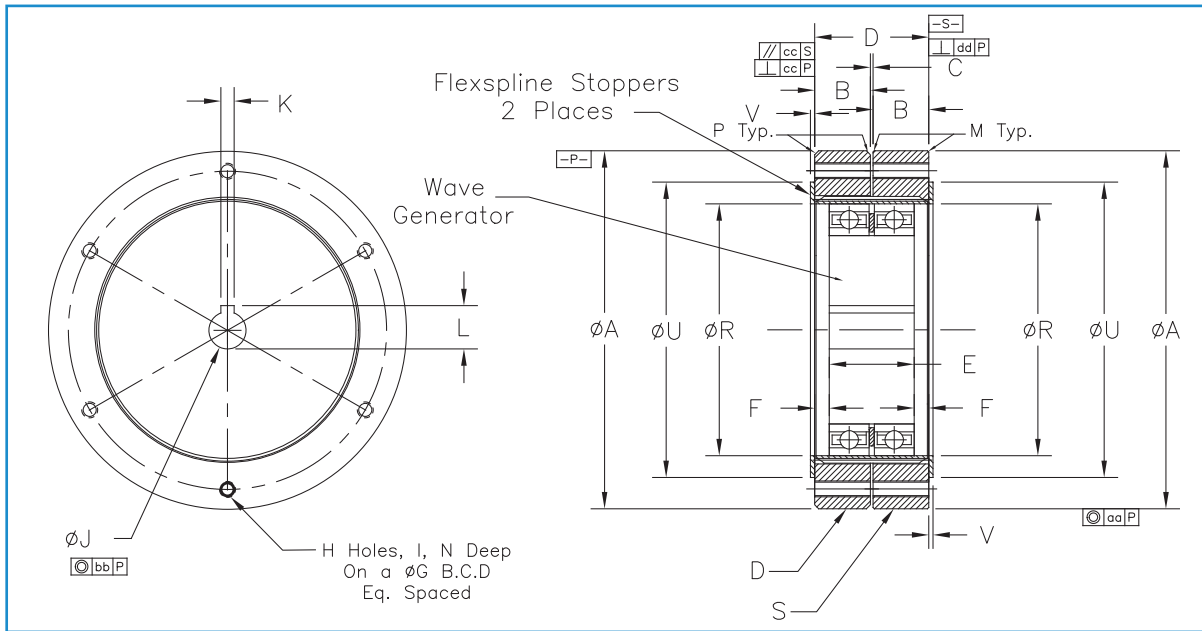
HDR Heavy Duty Pancake Series

The HDR Series is a heavy duty pancake design that utilizes a double bearing wave generator and wider splines than the HDF Series. The HDR is commonly used in heavy service load applications where shock loads are present, such as corrugated machinery and printing press cutters. The HDR offers low backlash and standard ratios from 80:1 to 200:1 with torque capacities up to 2000 Nm. Custom drives are available upon request.



Size	Maximum Input Speed		Ratio	Input Speed 3000 rpm			Input Speed 1500 rpm			Input Speed 1000 rpm		
				Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power
	Grease	Oil		Nm	rpm	kw	Nm	rpm	kw	Nm	rpm	kw
20	3500	5000	80	25	37.5	0.123	25	18.8	0.059	25	12.5	0.039
			84	25	35.7	0.117	25	17.9	0.056	25	11.9	0.037
			100	30	30	0.118	33	15	0.062	33.6	10	0.041
			120	30	25	0.101	37.5	25	0.06	33.6	25	0.042
			126	30	24	0.097	37.5	12	0.058	43.5	8	0.044
25	3000	5000	80	40	37.5	0.197	40	18.8	0.094	40	12.5	0.062
			100	50	30	0.197	55	15	0.104	56	10	0.069
			120	50	25	0.169	62.5	12.5	0.101	72.5	8.3	0.074
			150	50	20	0.146	62.5	10	0.085	72.5	6.7	0.062
			160	50	18.8	0.139	62.5	9.4	0.078	72.5	6.3	0.057
32	3000	4500	80	100	37.5	0.493	100	18.8	0.235	100	12.5	0.153
			100	120	30	0.473	132	15	0.248	135	10	0.165
			135	120	22.2	0.363	150	11.2	0.215	175	7.5	0.163
			160	120	18.8	0.312	150	9.4	0.185	175	6.3	0.014
			200	120	15	0.264	150	7.5	0.156	175	5	0.118
40	3000	4500	80	200	37.5	0.986	200	18.8	0.469	200	12.5	0.305
			84	200	35.7	0.939	200	17.9	0.447	200	11.9	0.291
			100	240	30	0.947	265	15	0.497	270	10	0.33
			125	240	24	0.777	300	12	0.462	300	8	0.3
			160	240	18.8	0.624	300	9.4	0.37	300	6.3	0.24
			168	240	17.9	0.594	300	8.9	0.352	300	6	0.228
			200	240	15	0.527	300	7.5	0.312	300	5	0.202
50	2500	3500	80	360	37.5	1.775	360	18.8	0.844	360	12.5	0.549
			100	450	30	1.775	495	15	0.929	505	10	0.617
			120	450	25	1.518	550	12.5	0.881	600	8.3	0.625
			150	450	20	1.25	550	10	0.723	600	6.7	0.513
			160	450	18.8	1.169	550	9.4	0.678	600	6.3	0.481
			200	450	15	0.989	550	7.5	0.572	600	5	0.405
65	1750	1750	80				800	18.8	1.876	800	12.5	1.221
			96				900	15.6	1.76	1015	10.4	1.335
			100				900	15	1.689	1015	10	1.282
			126				1000	11.9	1.558	1150	7.9	1.162
			132				1000	11.4	1.487	1150	7.6	1.11
			135				1000	11.2	1.454	1150	7.4	1.086
			160				1000	9.4	1.233	1150	6.3	0.921
			200				1000	7.5	1.04	1150	5	0.776
80	1500	1500	80				1500	18.8	3.518	1500	12.5	2.289
			100				1800	15	3.377	2000	10	2.442
			125				2000	12	3.077	2300	8	2.301
			168				2000	8.9	2.348	2300	6	1.755
			200				2000	8.9	2.079	2300	5	1.552
			250				2000	6	1.758	2300	4	1.311

HDR-M1 Dimensions



Size						
	20	25	32	40	50	65
ØA	70 ⁺⁰ _{-0.019}	85 ⁺⁰ _{-0.022}	110 ⁺⁰ _{-0.022}	135 ⁺⁰ _{-0.025}	170 ⁺⁰ _{-0.025}	215 ⁺⁰ _{-0.029}
B	12	14	18	21	26	35
C	1	1	1	1	1	1
D	25	29	37	43	53	71
E	17.3	20	25.9	31.5	39.1	50.5
F	3.85	4.5	5.55	5.75	6.95	10.25
ØG	60	75	100	120	150	195
H	6	6	6	6	6	6
I	M3x0.5	M4x0.7	M5x0.8	M6x1	M8x1.25	M10x1.5
ØJ	9 ^{+0.015} ₋₀	11 ^{+0.018} ₋₀	14 ^{+0.018} ₋₀	14 ^{+0.018} ₋₀	19 ^{+0.021} ₋₀	24 ^{+0.021} ₋₀
ØK	3 ^{±0.0125}	4 ^{±0.015}	5 ^{±0.015}	5 ^{±0.015}	6 ^{±0.015}	6 ^{±0.018}
L	10.4	12.8	16.3	16.3	21.8	27.3
M	0.4	0.4	0.4	0.4	0.4	0.4
N	6	8	10	12	16	20
ØR	47	59	77	95	119	150
ØU	54.8	69.7	92.6	111.4	135	177
V	1 ^{+0.13} ₋₀	1 ^{+0.13} ₋₀	1 ^{+0.13} ₋₀	1.78 ^{+0.13} ₋₀	1.78 ^{+0.13} ₋₀	1.78 ^{+0.13} ₋₀
aa	0.016	0.016	0.017	0.019	0.024	0.027
dd	0.01	0.012	0.012	0.012	0.015	0.015
cc	0.017	0.024	0.026	0.026	0.028	0.034
bb	0.013	0.016	0.016	0.017	0.021	0.025
Weight kg (lb)	0.5 (1.1)	0.8 (1.8)	1.7 (3.7)	3 (6.6)	6 (13.2)	12 (26.5)

HDA-M1 DRAWING NOTES

- [A] ITEM 1 STATIC CIRCULAR SPLINE MARKED "S"
 ITEM 2 ONLY APPEARS WITH HDR & HDA
 ITEM 3 DYNAMIC CIRCULAR SPLINE MARKED "D"
 ITEM 4 FLEXSPLINE
 ITEM 5 WAVE GENERATOR
 ITEM 6 WEAR WASHERS

- [B] DIMENSIONS MARKED 1 ESTABLISH INTERFACE AND INSTALLATION REQUIREMENTS, AND MUST BE MAINTAINED UNDER ALL OPERATING CONDITIONS.
 [C] DIMENSIONS MARKED 2 ARE NECESSARY TO LOCATE WEAR WASHERS, ITEM 6, IN CORRECT POSITION.
 [D] DRAWING IS FOR DIMENSIONAL REVIEW ONLY. **DO NOT SCALE**

HDB Back-to-Back 1:1 Pancake Series

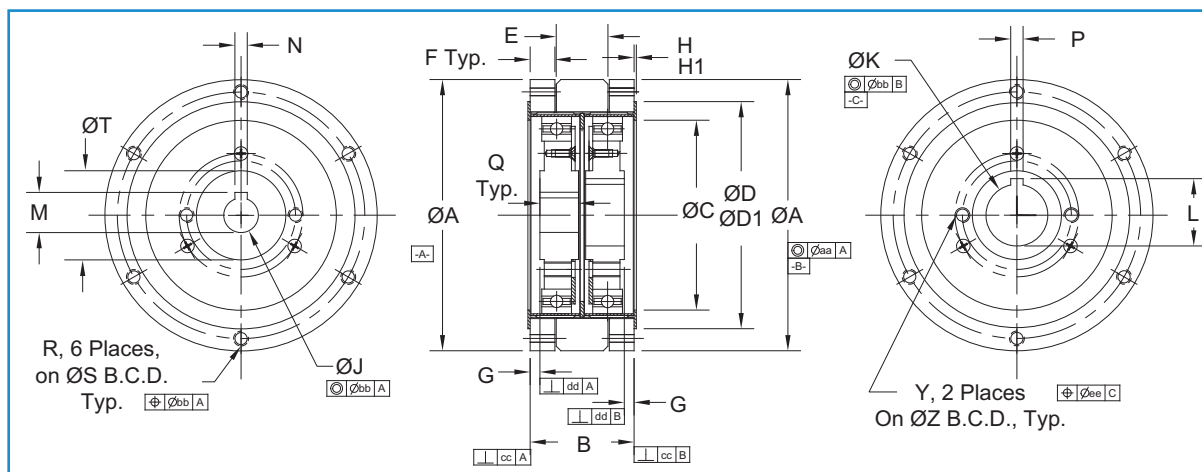
The HDB Series is a 1:1 double pancake design used for phase shifting differential applications. It is most often used in printing, converting, and packaging machinery where the wave generator is held stationary except when making intermittent registration / phase shifting adjustments. Conic Systems also offers the HDB packaged in a complete shaft mount differential gearbox.



HDB Specifications

Size	Ratio	Input Speed 3000rpm			Input Speed 1500rpm			Input Speed 1000rpm		
		Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power	Output Torque	Output Speed	Input Power
		Nm	rpm	kw	Nm	rpm	kw	Nm	rpm	kw
20	80	15	37.5	0.096	15	18.8	0.049	15	12.5	0.033
	84	15	35.7	0.092	15	17.9	0.047	15	11.9	0.031
	100	18	30	0.092	20	15	0.052	22	10	0.038
	120	20	25	0.085	22.5	12.5	0.049	25	8.3	0.036
	126	20	23.8	0.081	22.5	11.9	0.047	25	7.9	0.034
25	80	25	37.5	0.160	25	18.8	0.082	27.5	12.5	0.060
	100	30	30	0.154	33	15	0.086	35	10	0.061
	120	32	25	0.137	35	12.5	0.076	38	8.3	0.055
	150	36	20	0.134	40	10	0.070	43.5	6.7	0.051
	160	36	18.8	0.126	40	9.4	0.066	40	6.3	0.043
32	80	55	37.5	0.353	55	18.8	0.180	55	12.5	0.120
	100	70	30	0.359	77	15	0.202	80	10	0.140
	135	80	22.2	0.332	88	11.1	0.170	97	7.4	0.125
	160	85	18.8	0.297	93.5	9.4	0.153	102	6.3	0.112
	200	85	15	0.238	93.5	7.5	0.122	102	5	0.089
40	80	100	37.5	0.641	100	18.8	0.328	100	12.5	0.218
	84	100	35.7	0.610	100	17.9	0.312	100	11.9	0.208
	100	120	30	0.615	132	15	0.346	135	10	0.236
	125	135	24	0.554	150	12	0.314	150	8	0.209
	160	150	18.8	0.524	165	9.4	0.271	165	6.3	0.181
	168	150	17.9	0.499	165	8.9	0.256	165	6	0.173
50	80	180	37.5	1.154	180	18.8	0.59	180	12.5	0.393
	100	220	30	1.128	240	15	0.628	245	10	0.428
	120	250	25	1.068	275	12.5	0.6	280	8.3	0.406
	150	280	20	1.044	310	10	0.544	320	6.7	0.374
	160	280	18.8	0.979	310	9.4	0.509	320	6.3	0.352
	200	280	17.9	0.783	310	7.5	0.406	320	5	0.279

HDB-M1 Dimensions



	20	25	32	40	50
ØA	70 ⁺⁰ _{-0.018}	85 ⁺⁰ _{-0.022}	110 ⁺⁰ _{-0.025}	134 ⁺⁰ _{-0.025}	170 ⁺⁰ _{-0.025}
B	26.5 ^{+0.25} ₋₀	34.8 ^{+0.25} ₋₀	42 ^{+0.6} ₋₀	56.5 ^{+0.8} ₋₀	See Drawing
ØC	47 ±0.51	59 ±0.51	77 ±0.51	95 ±0.51	119 ±0.51
ØD	54 ±0.51	69.4 ±0.51	92.1 ±0.51	111.1 ±0.51	134.4 ±0.51
ØD1	54.7 ^{+0.51} ₋₀	70.2 ^{+0.51} ₋₀	92.9 ^{+0.38} ₋₀	92.9 ^{+0.38} ₋₀	135.2 ^{+0.38} ₋₀
E	14 ±0.1	18 ±0.1	20.9 ±0.1	28 ±0.1	35 ±0.2
F	6 ±0.1	8 ±0.2	10 ±0.2	13 ±0.2	13 ±0.2
G	1.8 ±0.51	3.27 ±0.51	3.95 ±0.51	1.95 ±0.51	1.4 ±0.51
H	0.81 ±0.13	0.81 ±0.13	0.81 ±0.13	1.57 ±0.13	1.57 ±0.13
H1	0.94 ^{+0.13} ₋₀	0.94 ^{+0.13} ₋₀	0.94 ^{+0.13} ₋₀	1.69 ^{+0.13} ₋₀	1.69 ^{+0.13} ₋₀
ØJ	9 ^{+0.015} ₋₀	11 ^{+0.018} ₋₀	14 ^{+0.02} _{-0.02}	14 ^{+0.02} _{-0.02}	19 ^{+0.02} _{-0.02}
ØK	16 ^{+0.013} ₋₀	19 ^{+0.013} ₋₀	25 ^{+0.02} ₋₀	25 ^{+0.02} ₋₀	35 ^{+0.023} ₋₀
L	17.4 ±0.1	20.8 ±0.1	27.3 ±0.2	27.3 ±0.2	38.3 ±0.2
M	10.4 ^{+0.1} ₋₀	12.8 ^{+0.1} ₋₀	16.3 ^{+0.1} ₋₀	16.3 ^{+0.1} ₋₀	21.8 ^{+0.1} ₋₀
N	3 ±0.0125	4 ±0.013	5 ±0.013	5 ±0.013	6 ±0.013
P	3 ±0.0125	4 ±0.013	5 ±0.013	5 ±0.013	10 ±0.023
Q	11.4	12.8	15.6	19.4	23.2
R	M4x0.7	M5x0.8	M6x1	M8x1.25	M10x1.5
ØS	60	75	100	120	150
ØT	20	28	36	32	50
Y	M4x0.7	M4x0.7	M6x1	M8x1.25	M8x1.25
ØZ	27	35	44	48	65
aa	0.07	0.076	0.078	0.088	0.098
bb	0.013	0.015	0.015	0.018	0.02
cc	0.018	0.023	0.025	0.025	0.025
dd	0.01	0.013	0.013	0.013	0.015
ee	0.25	0.25	0.25	0.25	0.25
Weight kg (lb)	0.7 (1.50)	1.23 (2.70)	2.14 (4.70)	4.09 (9.00)	6.9 (15.3)

Driving Arrangements

Conic Systems harmonic gearing can be used with a number of input, output, and fixed element drive variations for speed reduction, speed increasing, and phasing differential applications. The arrangements that apply are illustrated below.

Cup Type:

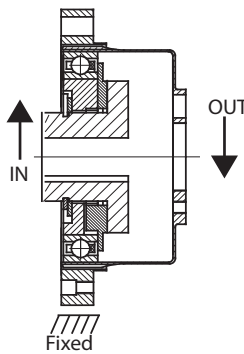
FS Flexspline
S Circular Spline
N Speed (RPM)
R Ratio
WG Wave Generator

Pancake Type:

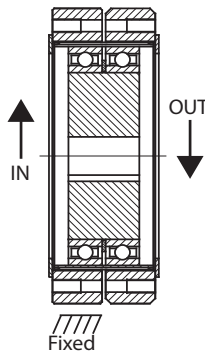
FS Flexspline
S Circular Spline
N Speed (RPM)
R Ratio
WG Wave Generator
D Dynamic Spline

1 Speed Reducer

$$N_{FS} = \frac{N_{WG}}{R}$$

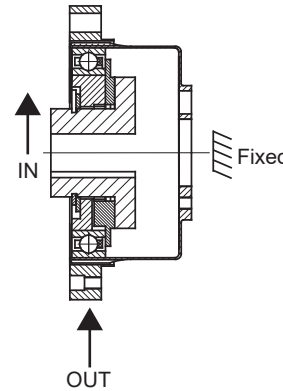


$$N_D = \frac{N_{WG}}{R}$$

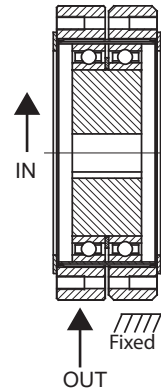


2 Speed Reducer

$$N_S = \frac{N_{WG}}{R+1}$$

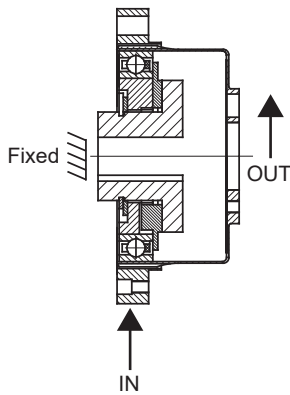


$$N_S = \frac{N_{WG}}{R+1}$$

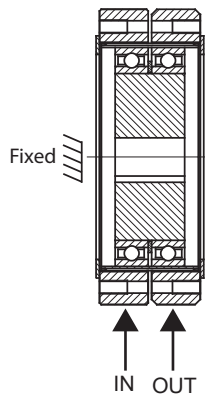


3 Speed Increaser

$$N_{FS} = N_S \cdot \left(\frac{R+1}{R}\right)$$

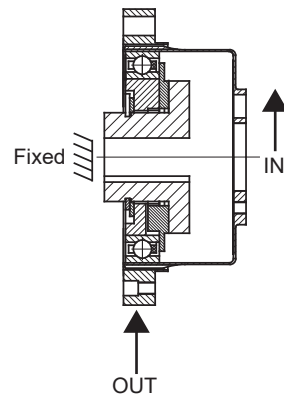


$$N_D = N_S \cdot \left(\frac{R+1}{R}\right)$$

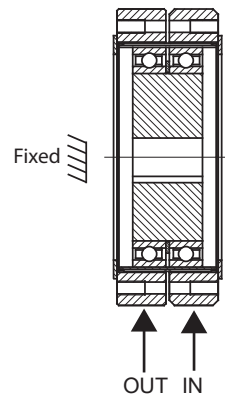


4 Speed Reducer

$$N_S = N_{FS} \cdot \left(\frac{R}{R+1}\right)$$

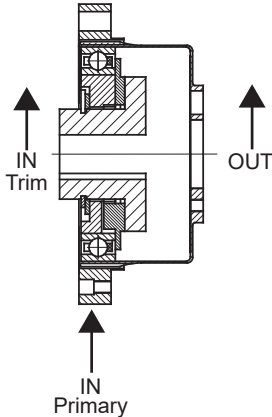


$$N_S = N_D \cdot \left(\frac{R}{R+1}\right)$$

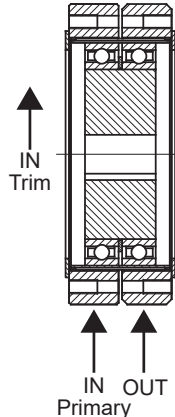


5 Differential Speed Reducer

$$N_D = \left[N_S \cdot \left(\frac{R+1}{R}\right) \right] - \frac{N_{WG}}{R}$$

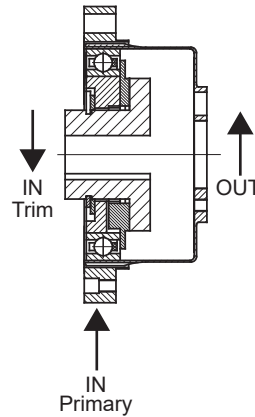


$$N_D = \left[N_S \cdot \left(\frac{R+1}{R}\right) \right] - \frac{N_{WG}}{R}$$

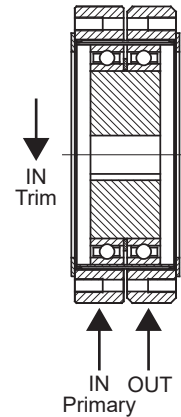


6 Differential Speed Reducer

$$N_{FS} = \left[N_S \cdot \left(\frac{R+1}{R}\right) \right] + \frac{N_{WG}}{R}$$

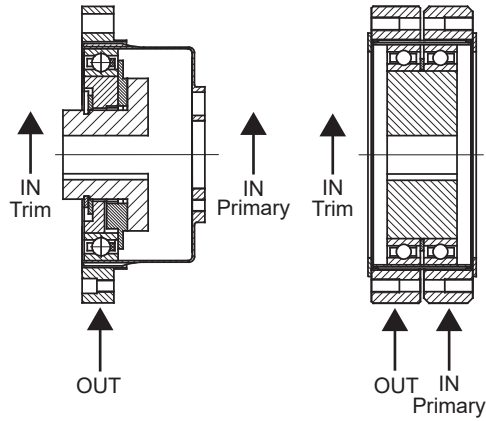


$$N_D = \left[N_S \cdot \left(\frac{R+1}{R}\right) \right] + \frac{N_{WG}}{R}$$



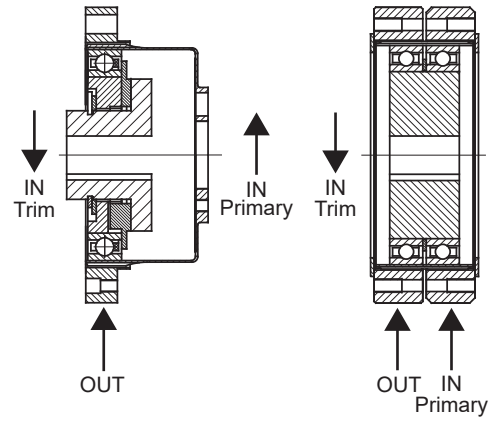
7 Differential Speed Reducer

$$N_S = \left[N_{FS} \cdot \left(\frac{R}{R+1} \right) \right] + \frac{N_{WG}}{R+1} \quad N_S = \left[N_D \cdot \left(\frac{R}{R+1} \right) \right] + \frac{N_{WG}}{R+1}$$



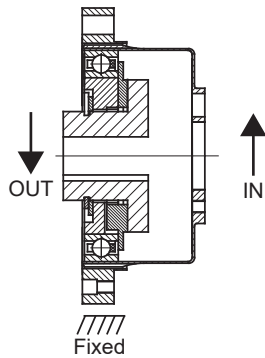
8 Differential Speed Reducer

$$N_S = \left[N_{FS} \cdot \left(\frac{R}{R+1} \right) \right] - \frac{N_{WG}}{R+1} \quad N_S = \left[N_D \cdot \left(\frac{R}{R+1} \right) \right] - \frac{N_{WG}}{R+1}$$



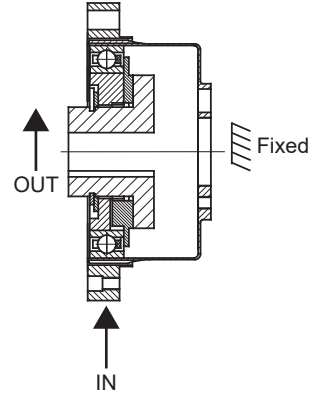
9 Speed Increaser 1:R

$$N_{WG} = N_{FS} \cdot R$$



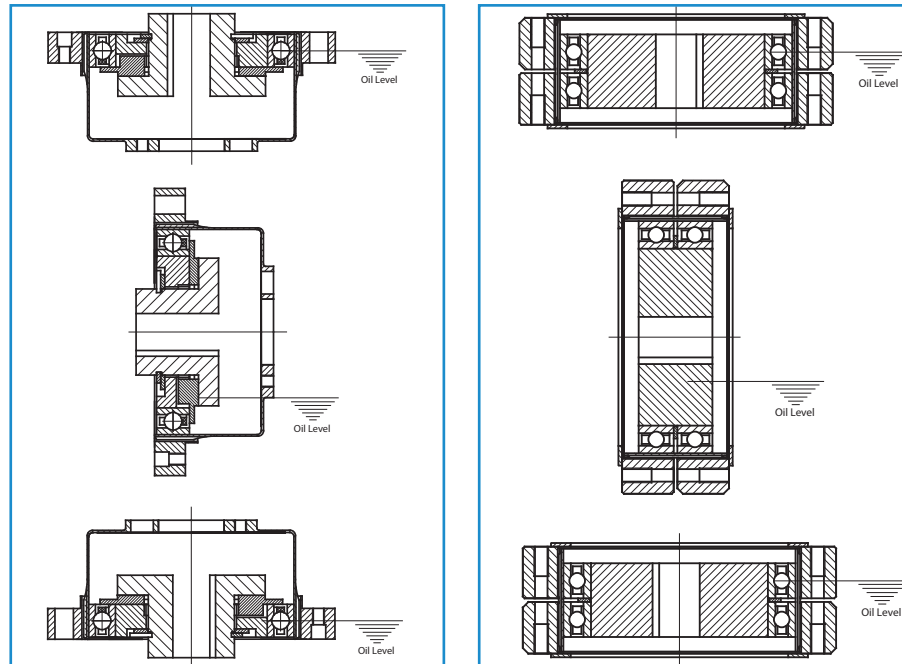
10 Speed Increaser 1:(R+1)

$$N_{WG} = N_S \cdot (R + 1)$$



Lubrication

Suggested oil levels are shown below. When using grease lubrication, the grease should be applied generously inside the flexspline, the wave generator bearings, and on the teeth of the circular spline. Fill approximately 30% of the volume with grease.



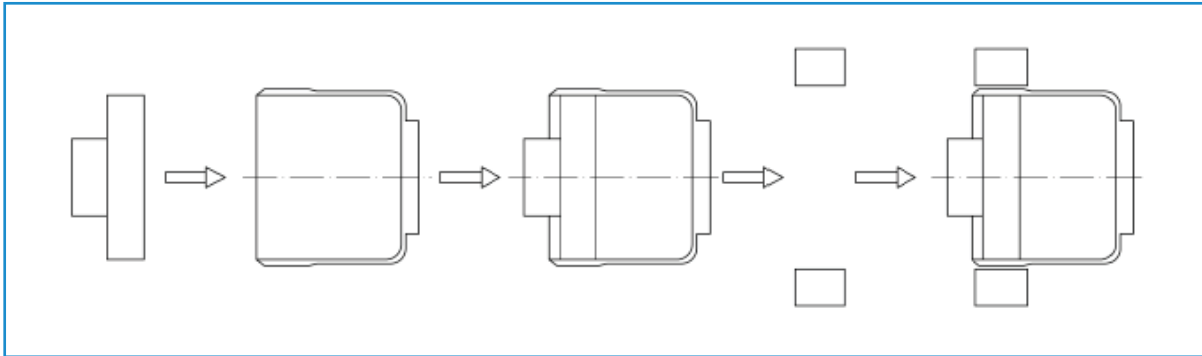
Oil Changes: Oil changes are suggested after 100 hours of operation and at intervals of 1000 running hours thereafter.

Grease Changes: When operating under nominal torque, grease should be changed after approximately 1000 hours of operation. Light duty operation may allow for longer intervals between changes. To change grease, completely disassemble and clean units before re-greasing.

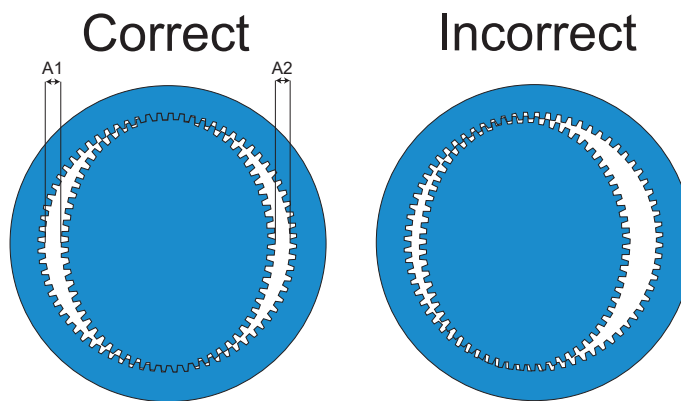
Component Assembly

- 1 Clean all components prior to assembly and installation.
- 2 The gearing components must be maintained as a matched set.
- 3 Coat the non-bolting surfaces of each component with a thin layer of lubricant to protect against rust and to ease assembly.
- 4 If dowel pins are used for flexspline mounting, match drill the output shaft prior to dowel pin installation.
- 5 When a clamp ring is used to mount an HDC flexspline, insure the ring OD is less than the diameter of the flexspline's mounting boss. Mounting rings require an adequate radius at its OD to prevent damage to the mating flexspline diaphragm surface.
- 6 To assemble, insert the wave generator into the open end of the flexspline. Slightly tilting the wave generator during installation may ease the process.

- 7 Slide the circular spline over the flexspline. For cup style harmonic gears, sliding from the closed end is generally easier and preferred. Slowly rotating the wave generator eases installation.



- 8 If possible, check the engagement symmetry to ensure there is an equal amount of space between the flexspline and circular spline where the teeth are not engaged. "A1" should be equal to "A2". If the assembly is not symmetric, disassemble and start the assembly process again. An incorrectly aligned assembly will function, but it will be subject to reduced life and performance.

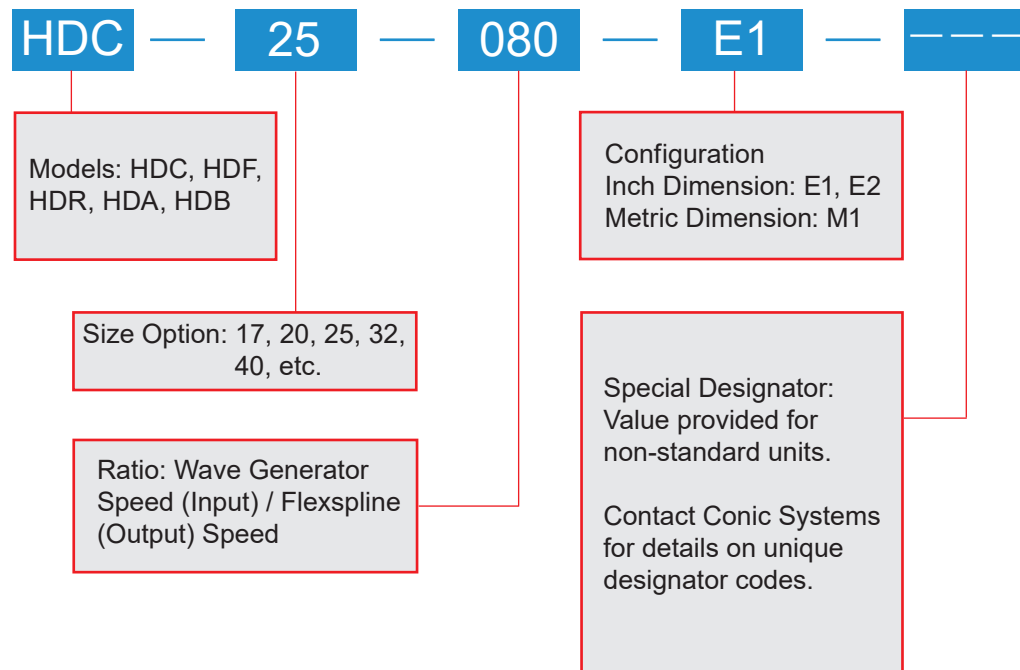


Technical Notes

Conic recommends limiting the maximum acceleration, deceleration, and momentary peak torque to 150% of the rated torque for most applications. If higher peak torque is required for a given drive, please contact Conic's Engineering Department for assistance in evaluating the drive's suitability for the applications.

Efficiency, spring rate, inertia, maximum speed, and back driving torque vary with drive size, style, and ratio. Contact Conic's Engineering Department for data on a particular drive selection.

Ordering Codes



Disclaimer

Notice: All efforts have been made to assure that the information in this catalog is complete and accurate. However, Conic Systems is not liable for any errors, omissions, or inaccuracies in the reported data. Conic Systems reserves the right to change the product specifications, for any reason, without prior notice. Customers are responsible for determining product applicability to any particular application.

Our History

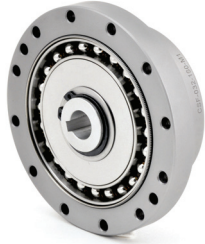
Since we introduced the first harmonic gearing differential in 1968, Conic Systems has been focused on providing the highest quality, longest lasting harmonic gearing systems and controls to customers worldwide. Today, our product lines include harmonic servo gearheads, speed changing and phase shifting harmonic differential transmissions, harmonic gearing component sets, and a wide array of industrial control modules. We also offer custom solutions, repair, replacement, and rebuilding services for all brand harmonics.

Equipment and capabilities include: super precision turning, 4 axis milling, Liebherr gear cutting, Wenzel involute and non-involute gear and cutter inspection, single flank spiral bevel gearing inspection, tactile and optical CMM measuring, metallurgical sampling/mounting/polishing, sub 1 arc-sec positional accuracy testing, 0.2 arc-sec repeatability testing resolution, programmable dynamic torque-speed testing, Rockwell hardness and Vickers micro hardness testing, dynamic FEA analysis, full compliment of manufacturing, engineering, and quality inspection equipment and software suites.



- 1968 Conic Systems is established in Fairfield, NJ and introduces the harmonic differential
- 1972 Conic introduces harmonic web tension infeed controls
- 1991 Conic introduces digital HDD draw control systems
- 1992 Operations move to Port Jervis, NY
- 1994 Conic introduces 1:1 HDB shaft mount harmonic differentials
- 1999 Conic introduces 1:1 and 2:1 CSF right angle speed changing harmonic gearboxes
- 2004 Conic acquires Datatran Labs
- 2007 Conic establishes NAC Harmonic Gearing in Jacksonville, FL
- 2016 Conic establishes Tetragon Labs in Jacksonville, FL for Research & Development
- 2018 Conic introduces harmonic gearing servo gearheads

Visit www.conicsystems.com for information on additional Conic product lines, engineering data, drawings, and 3D model downloads.



CSF Short Cup Series – A high performance, compact, zero backlash series of drives. The CSF utilizes a proprietary non-involute tooth form for greater load capacities and is offered in standard sizes with nominal capacities to 647 Nm and ratios of 50:1 to 160:1.



LT Lifetime Series Servo Gearheads – Available in four sizes with nominal capacities to 120 Nm, the LT Series offers the advantages of zero backlash harmonic gearing in an industrial servo gearhead. It is available in NEMA 17, 23, 34, & 42 mounts as well as metric configurations with adapters to meet customer specified motor mounting requirements.



CSF and SHF Units with Integrated Cross Roller Bearings – Designed to meet common configurations of robotic and automation applications, Conic offers enclosed drives with integrated cross roller bearings. These compact, high performance designs simplify mounting and are customizable to meet customer requirements.



Custom Engineered Drives – Conic offers custom harmonic gearing solutions to meet application needs. Examples include ultra-short cup designs for robotic and medical applications and low cost drives for high volume automotive and energy applications.



Right Angle, Shaft Mount & Foot Mount Harmonic Differentials – Conic offers a wide variety of speed changing & phase shifting harmonic differential transmissions. Typically used in printing, packaging, and converting applications, Conic harmonic differentials are designed to withstand high loads in demanding applications like chill stands and rotary cutters. Units are offered in nominal capacities to 4000 Nm.



Harmonic Gearing Systems Since 1968

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